VGP352 – Week 4

- Agenda:
 - Quiz #1
 - BRDFs, part 1
 - Common ideas and terminology
 - Micro-facet based BRDFs
 - Cook-Torrance BRDF

- Bi-directional reflectance distribution function
 - Notation is $f(\omega_0, \omega_i)$
 - "...describes the ratio of reflected radiance exiting from a surface in a particular direction (defined by the vector $\omega_{_{0}}$) to the irradiance incident on the surface from direction $\omega_{_{i}}$ over a particular waveband."

- In English...
 - Given an arbitrary input direction, ω_{i} , and an arbitrary output direction, ω_{o} , we can calculate the ratio of energy (light) transferred from ω_{i} to ω_{o}
- What does this tell us?

In English...

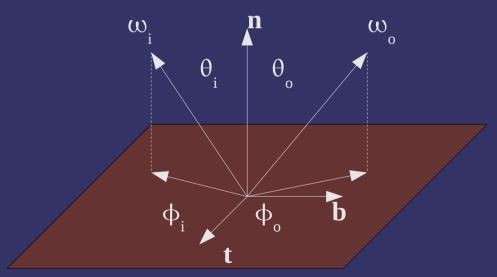
Given an arbitrary input direction, ω_i , and an arbitrary output direction, ω_o , we can calculate the ratio of energy (light) transferred from ω_i to ω_o

What does this tell us?

- If we know where the light is coming from, we can calculate how much of the light is reflected in any direction
- If we know a light reflection direction (i.e., viewing direction) we can calculate the contribution of every possible light input direction

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- \triangleright ω consists of the two angles:
 - θ is the elevation angle, and it is measured relative to the surface normal
 - $\overline{}$ $\overline{}$ $\overline{}$ is the azimuth angle, and it is measured relative to the surface tangent



- \Rightarrow w is a solid angle
 - "The solid angle, Ω , is the angle in three-dimensional space that an object subtends at a point. It is a measure of how big that object appears to an observer looking from that point."
 - Each ω is a direction and a "slice" from the volume of the hemisphere around the point in question



 \triangleright Why is it significant that ω is a solid angle?

- ightharpoonup Why is it significant that ω is a solid angle?
 - The size of a light observed by the receiver matters!
 - At 20.3 light years, Earth gets no illumination from Glisse 581 → it looks tiny and has an infinitesimal solid angle
 - At ~2M miles, the planet orbiting Glisse
 581 gets lots of illumination from it → it looks big and a bigger solid angle
 - 0.00000024° vs. 1.28°

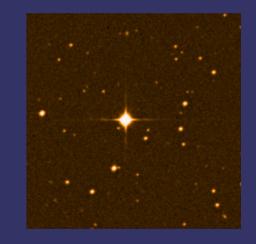


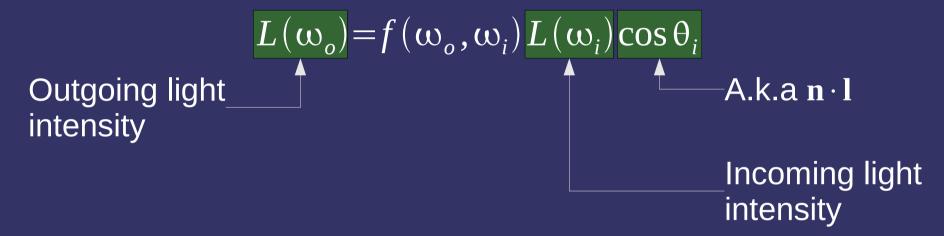


Image from http://en.wikipedia.org/wiki/Gliese_581

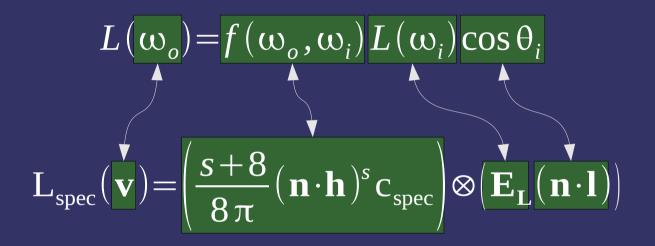
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The amount of light reflected from a particular input vector to a particular output vector:



Note the similarities with our existing lighting mode:



What if we want to calculate the amount light reflected to a particular output vector from all possible input vectors?

What if we want to calculate the amount light reflected to a particular output vector from all possible input vectors?

$$L(\omega_o) = \int_{\Omega} f(\omega_o, \omega_i) L(\omega_i) \cos \theta_i d\omega_i$$

- Integration over a solid angle works just like any other integration
- This integral is over the hemisphere above the point
 - This is a solid angle of 2π
- Most BRDFs will contain a $1/\pi$ factor because of this

BRDF Properties

- Physically based BRDFs have two important properties:
 - Helmoltz reciprocity:

$$f(\omega_i, \omega_o) = f(\omega_o, \omega_i)$$

- Also called Helmoltz Stereopsis
- This is the "bi-directional" part of BRDF

BRDF Properties

- Physically based BRDFs have two important properties:
 - Conservation of energy:

$$\forall \ \omega_i, \int_{\Omega} f(\omega_i, \omega_o) \cos \theta_o d \omega_o \leq 1$$

- In other words, the output energy is less than or equal to the input energy.
- The magic (8+s)/8 term in the modified Blinn-Phong equation conserves energy.

Where do BRDFs come from?

- Measured BRDFs
 - Measure every possible output from every possible output
 - Oregon BRDF Library (and others) have data captured from these instruments available

Measured BRDFs



Image from http://www.merl.com/projects/facescanning/

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Measured BRDFs

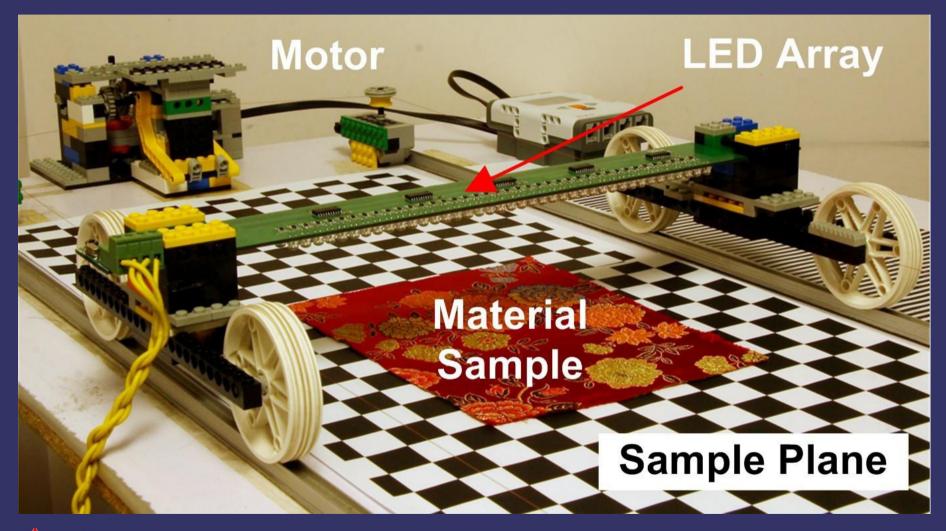


Image from http://www.shuangz.com/projects/aniso/

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References

Wang, J., Zhao, S., Tong, X., Snyder, J., and Guo, B. 2008.
Modeling anisotropic surface reflectance with example-based microfacet synthesis. In ACM SIGGRAPH 2008 Papers (Los Angeles, California, August 11 - 15, 2008). SIGGRAPH '08. ACM, New York, NY, 1-9. http://www.shuangz.com/projects/aniso/

McGuire, An Inexpensive Light Stage Dome. *Journal of Graphics, GPU, and Game Tools*, 2009.

Sample BRDF data sets:

http://www.graphics.cornell.edu/online/measurements/reflectance/index.html

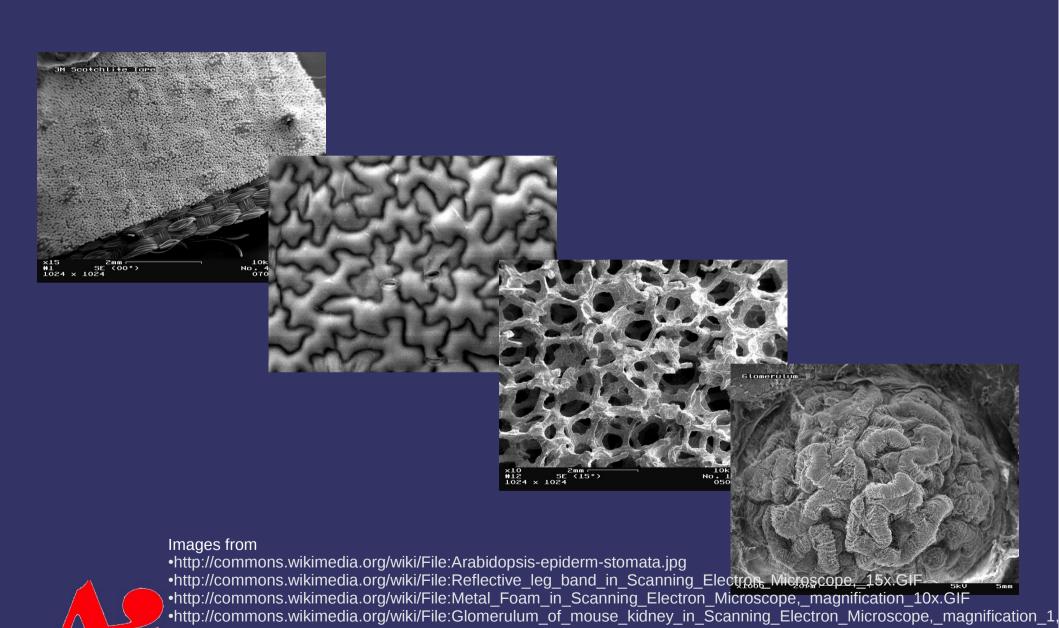
http://www1.cs.columbia.edu/CAVE//software/curet/

http://math.nist.gov/~FHunt/appearance/obl.html



Where do BRDFs come from?

- Analytical BRDFs
 - Mathematical models used to reproduce observed behavior
 - May be derived from simplified measured data



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- Surfaces are made of numerous infinitesimal subsurfaces (aka micro-facets)
 - Each micro-facet acts as a perfect mirror
 - Micro-facet normals are randomly distributed according to some distribution function $p(\mathbf{h})$
 - Micro-facets can obscure other micro-facets both from the light and from the viewer

Implications:

- Light is only reflected along the ideal reflection vector of each micro-facet
- Distribution of the normals of these micro-facet determines how specular the surface appears
- Amount of internal occlusion limits reflection

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Determining the number of facets with $\mathbf{n} = \mathbf{h}$ that are visible to \mathbf{v} and \mathbf{l} is enough to determine the BRDF.

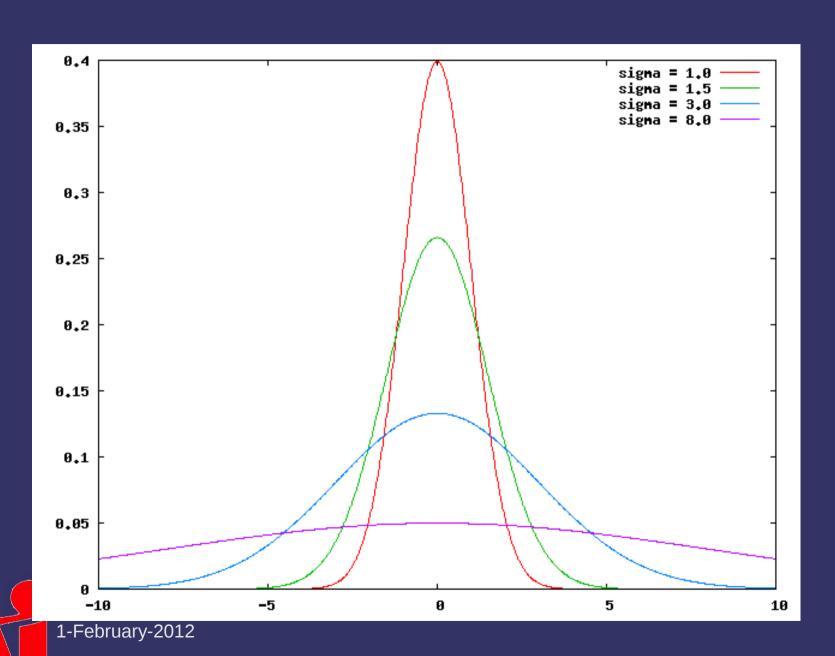
- BRDF is determined by:
 - Fresnel term
 - Fraction of micro-facets with n = h
 - Fraction of micro-facets visible to both I and ${f v}$
 - Non-visible to I is often called "shadowing"
 - Non-visible to \mathbf{v} is often called "masking"
 - Both can just be called "occlusion"

- Micro-facet normals are random, but follow some distribution function
 - Given n, determine the fraction of micro-facet normals that point towards h
 - Sometimes called the normal distribution function (NDF)
 - Can use arbitrary function to calculate this probability
 - May be convenient to encode this in a texture
 - Gaussian or standard normal distribution function seems like a good choice
 - The more different the h is from n, the lower the probability

Gaussian distribution:

$$P(\theta) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\left(\frac{\theta^2}{2\sigma^2}\right)}$$

 σ is the standard deviation



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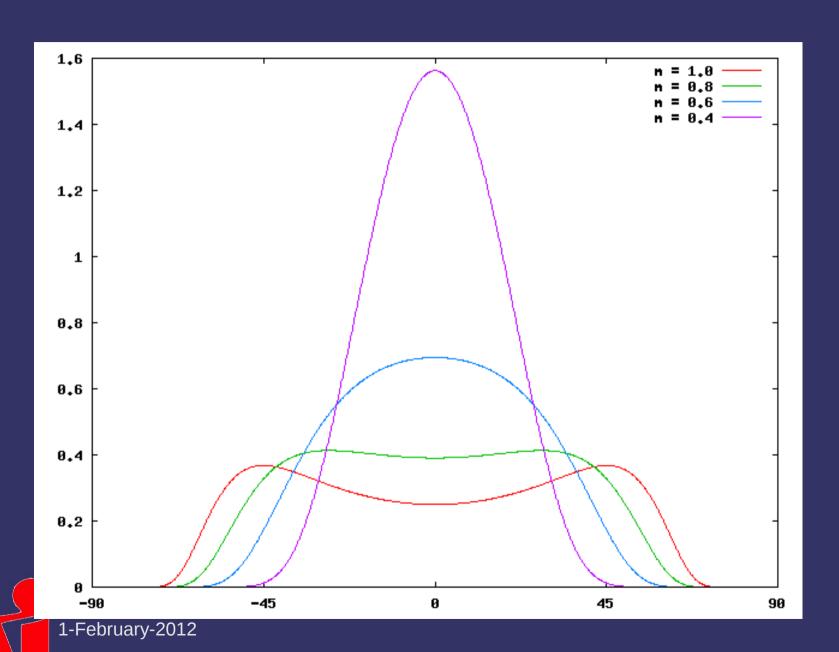
- Looking at the graph, why is this distribution unsuitable?
 - As σ increases, the effective range increases to ∞
 - Cook-Torrance paper includes a scaling factor to counteract this, but it's fidgety.
 - Distribution is based on θ , but we only know $\cos(\theta)$

Beckmann distribution:

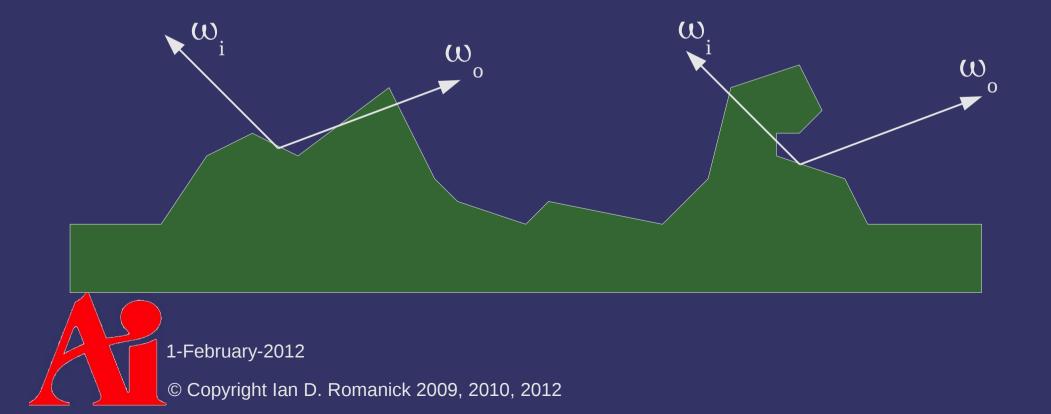
$$P(\theta) = \frac{1}{4 m^2 \cos^4 \theta} e^{-\left(\frac{\tan^2 \theta}{m^2}\right)}$$

m is average slope of the surface micro-facets

- Physically based model of rough surfaces
 - Based on Petr Beckmann's research in the early 60s
- \Rightarrow All calculations are based on $\cos(\theta)$!
 - Remember: $tan^2(\theta)$ is $(1 cos^2(\theta)) / cos^2(\theta)$



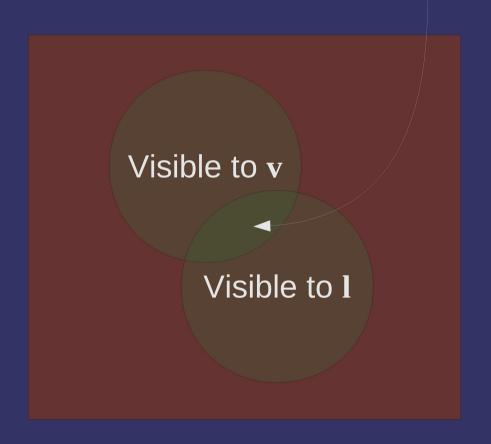
- A facet only contributes if it is visible to both **v** and **l**
 - Need to know the probability of a facet being visible



- Determine the probability of a facet being visible to the light and to the viewer
 - Use one probability function, $P_{vis}(\theta)$, for the probability of visibility to either **I** or **v**
 - Assume that visibility and orientation are uncorrelated

ightharpoonup Given $P_{vis}(\theta_{v})$ and $P_{vis}(\theta_{l})$, what is $P_{vis}(\theta_{v} \cap \theta_{l})$?

Visible to I and to \mathbf{v}





- \triangleright Given $P_{vis}(\theta_{v})$ and $P_{vis}(\theta_{l})$, what is $P_{vis}(\theta_{v} \cap \theta_{l})$?
 - Calculating $P(A \cap B)$ from P(A) and P(B) is hard, in general.
 - $P_{vis}(\theta_{v}) \times P_{vis}(\theta_{l}) < P_{vis}(\theta_{v} \cap \theta_{l})$
 - $\overline{-P(A)P(B)} = \overline{P(A \cap B)} \leftrightarrow A$ and B are independent
 - Visibility to the light and viewer are not independent
 - Example: Put the light and viewer at the same location
 - Different BRDFs use different methods

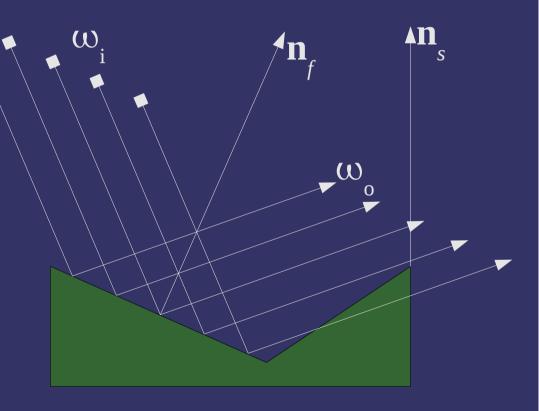
- Simplifying assumption:
 - Model the surface as a bunch of parallel grooves
 - Grooves magically keep the same orientation relative to the viewer no matter how the surface is oriented

How do we estimate $P_{vis}(\theta)$?

- Clearly ω_i , ω_o , \mathbf{n}_f , and \mathbf{n}_g are involved

 $\overline{\mathbf{n}_{f}}$ is the facet normal

- \mathbf{n}_{s} is the surface normal



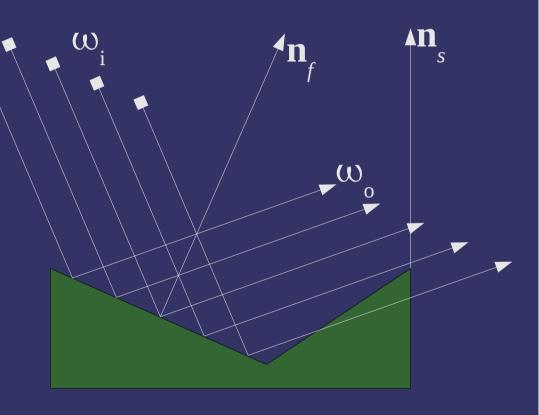
Observations:

Occlusion increases as:

$$- \angle \mathbf{n}_f \mathbf{n}_s \to 90^\circ \Leftrightarrow (\mathbf{n}_f \cdot \mathbf{n}_s) \to 0$$

$$- \angle \omega \mathbf{n}_s \to 90^{\circ} \Leftrightarrow (\omega \cdot \mathbf{n}_s) \to 0$$

$$- \angle \omega \mathbf{n}_f \to 0^\circ \Leftrightarrow (\omega \cdot \mathbf{n}_f) \to 1$$

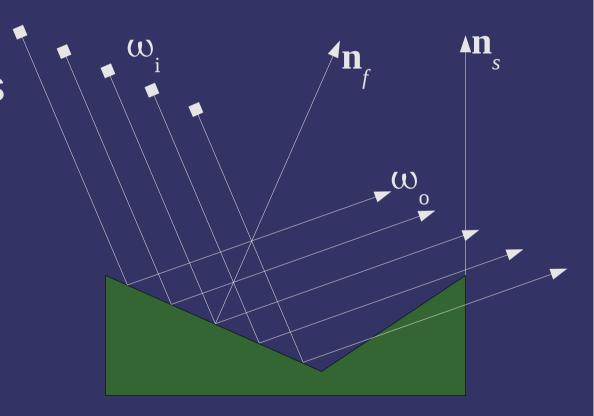




Cook-Torrance uses:

$$P_{v}(\theta) = \frac{2(\mathbf{n}_{s} \cdot \mathbf{n}_{f})(\mathbf{n}_{s} \cdot \omega)}{\omega \cdot \mathbf{n}_{f}}$$

What other vector is equivalent to n_f?



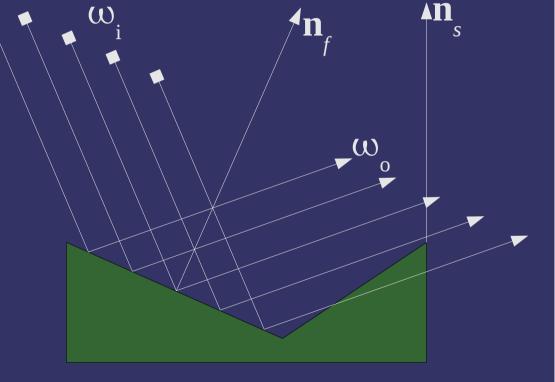
Cook-Torrance uses:

$$P_{v}(\theta) = \frac{2(\mathbf{n}_{s} \cdot \mathbf{n}_{f})(\mathbf{n}_{s} \cdot \omega)}{\omega \cdot \mathbf{n}_{f}}$$

- What other vector is equivalent to \mathbf{n}_f ?
 - By definition, $\overline{\mathbf{n}_f} = \overline{\mathbf{h}}$

$$G_{\mathbf{v}} = \frac{2(\mathbf{n} \cdot \mathbf{h})(\mathbf{n} \cdot \mathbf{v})}{\mathbf{v} \cdot \mathbf{h}}$$

$$G_{\mathbf{l}} = \frac{2(\mathbf{n} \cdot \mathbf{h})(\mathbf{n} \cdot \mathbf{l})}{\mathbf{l} \cdot \mathbf{h}}$$



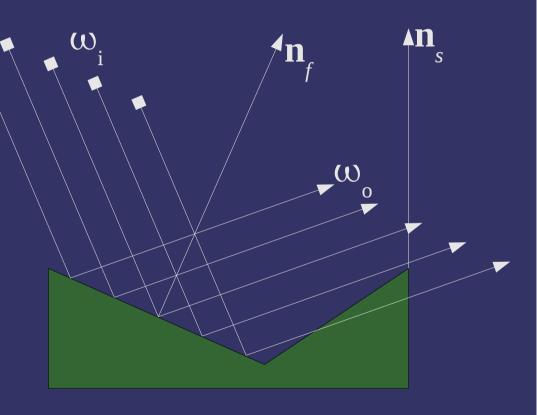


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This turns out to be a poor model

Real surfaces aren't made of long, V-shaped channels

 The reading for next week addresses this as well



Cook-Torrance BRDF

- One of the oldest BRDFs used in graphics
 - Published by Robert Cook and Ken Torrance in 1982
 - Cook was at Lucasfilm, Ltd.
 - Torrance was at Cornell
 - Based on micro-facets

Cook-Torrance BRDF

$$f(\omega_{o}, \omega_{i}) = \mathbf{k}_{d} f_{d} + \mathbf{k}_{s} f_{s}(\omega_{o}, \omega_{i})$$

$$f_{d} = 1/\pi$$

$$f_{s}(\omega_{o}, \omega_{i}) = 1/\pi \frac{F \times D(\mathbf{n} \cdot \mathbf{h}) \times G(\mathbf{n} \cdot \omega_{i}, \mathbf{n} \cdot \mathbf{h}, \mathbf{n} \cdot \omega_{o})}{(\mathbf{n} \cdot \omega_{i})(\mathbf{n} \cdot \omega_{o})}$$

- F is the Fresnel factor
- D is the distribution of micro-facet normals
- G is the geometry occlusion factor
- h is the half-vector from the Blinn-Phong lighting equation

Cook-Torrance Diffuse Factor

Cook-Torrance diffuse factor:

$$f_d = 1/\pi$$

Lambertian diffuse factor:

$$\mathbf{k}_{d} = \mathbf{n} \cdot \mathbf{l}$$

Remember how the BRDF is used:

$$L(\omega_o) = f(\omega_o, \omega_i) L(\omega_i) \cos \theta_i$$

- We just want to scale the incoming energy by the total angle and let the built in $(\mathbf{n}\cdot\boldsymbol{\omega}_{_{_{\!1}}})$ do the rest
- _ Remember ω_i≅I



Cook-Torrance Normal Distribution

- Cook-Torrance uses the Beckmann Distribution:
 - -m is a parameter that controls the smoothness of the surface

$$D(\mathbf{n} \cdot \mathbf{h}) = \frac{1}{4 m^2 (\mathbf{n} \cdot \mathbf{h})^4} e^{\left(\frac{(\mathbf{n} \cdot \mathbf{h})^2 - 1}{(\mathbf{n} \cdot \mathbf{h})^2 m^2}\right)}$$

Cook-Torrance Geometry Occlusion

Represents the decrease in light transmission caused by occlusion of the light or viewer by other micro-facets

$$G(\mathbf{n}\cdot\mathbf{\omega}_{i},\mathbf{n}\cdot\mathbf{h},\mathbf{n}\cdot\mathbf{\omega}_{o}) = \min\left[1,\frac{2(\mathbf{n}\cdot\mathbf{h})(\mathbf{n}\cdot\mathbf{\omega}_{o})}{\mathbf{\omega}\cdot\mathbf{h}},\frac{2(\mathbf{n}\cdot\mathbf{h})(\mathbf{n}\cdot\mathbf{\omega}_{i})}{\mathbf{\omega}\cdot\mathbf{h}}\right]$$

- Why aren't there any subscripts on ω in the denominators?
 - Hint: $\omega_{i} \cong \mathbf{I}$ and $\omega_{o} \cong \mathbf{v}$

Cook-Torrance Geometry Occlusion

Represents the decrease in light transmission caused by occlusion of the light or viewer by other micro-facets

$$G(\mathbf{n}\cdot\mathbf{\omega}_{i},\mathbf{n}\cdot\mathbf{h},\mathbf{n}\cdot\mathbf{\omega}_{o}) = \min\left[1,\frac{2(\mathbf{n}\cdot\mathbf{h})(\mathbf{n}\cdot\mathbf{\omega}_{o})}{\mathbf{\omega}\cdot\mathbf{h}},\frac{2(\mathbf{n}\cdot\mathbf{h})(\mathbf{n}\cdot\mathbf{\omega}_{i})}{\mathbf{\omega}\cdot\mathbf{h}}\right]$$

- Why aren't there any subscripts on ω in the denominators?
 - Hint: $\omega_{i} \cong \mathbf{I}$ and $\omega_{o} \cong \mathbf{v}$
 - h is half way between v and I:

$$\angle \mathbf{l} \mathbf{h} = \angle \mathbf{v} \mathbf{h} : (\mathbf{h} \cdot \mathbf{\omega}_{i}) = (\mathbf{h} \cdot \mathbf{\omega}_{o})$$

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References

http://wiki.gamedev.net/index.php/D3DBook:(Lighting)_Cook-Torrance http://en.wikipedia.org/wiki/Specular_highlight#Beckmann_distribution Philip Dutré. "Global Illumination Compendium." Computer Graphics, Department of Computer Science Katholieke Universiteit Leuven. 2003. http://www.cs.kuleuven.ac.be/~phil/GI/

Reading for Next Week

Prepare for next week:

Gregory J. Ward. 1992. Measuring and modeling anisotropic reflection. In *Proceedings of the 19th annual conference on Computer graphics and interactive techniques* (SIGGRAPH '92), James J. Thomas (Ed.). ACM, New York, NY, USA, 265-272. http://www.cs.virginia.edu/~gfx/courses/2006/DataDriven/bib/appearance/ward92.pdf

NOTE: This is different than what is (was) listed in the syllabus!

Next week...

- Quiz #2
- More BRDFs
 - Anisotropic reflection
 - Ward BRDF
 - Ashikhmin BRDF
 - Metals
 - How do metals "reflect" light?
 - Lafortune BRDF

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