

VGP352 – Week 6

⇒ Agenda:

- Illuminating infinitesimal strands
 - Piles of math leading to the Banks BRDF
 - General “strand” model for anisotropic surfaces
- Goldman's “fakefur”
- Implementing BRDFs in real-time
- Fins-and-shells for fur



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Hair

- ⇒ How do we calculate illumination for an infinitesimal strand or fiber?



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Terminology – Codimension

⇒ Definition:

Given an object of dimension n in a k dimensional space, with $k > n$, the codimension, c , is equal to $k - n$

- For a surface in 3-space, $n = 2$ and $k = 3$
 - When $c = 1$, we can trivially assign a normal to the object



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- For a surface in 3-space, $n = 2$ and $k = 3$
 - When $c = 1$, we can trivially assign a normal to the object
- For a line in 3-space, $n = 1$ and $k = 3$
 - When $c > 1$, things get a little weird...



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Terminology – Codimension

- Another way to think of it: The normal has c degrees of freedom
 - For a plane in 3-space, the normal can point in one of two directions (up or down)
 - $k - n = c \Rightarrow 3 - 2 = 1$
 - It's only degree of freedom is its magnitude
 - If we restrict the space to normalized vectors, there are only two possible values



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Terminology – Vector Spaces

⇒ Definition:

A vector space is a mathematical structure formed by a collection of vectors: objects that may be added together and multiplied ("scaled") by numbers, called scalars in this context.¹



¹From http://en.wikipedia.org/wiki/Vector_space

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Terminology – Vector Spaces

- T is the tangent-space at some point on the object
 - Vector space tangent to the point on the object
 - Specifically, all of the possible tangent vectors at that location
 - Has dimension k (same as the object)
- N is the normal-space at some point on the object
 - Vector space orthogonal to T
 - Specifically, all of the possible normal vectors at that location
 - Has dimension c (codimension of the object)

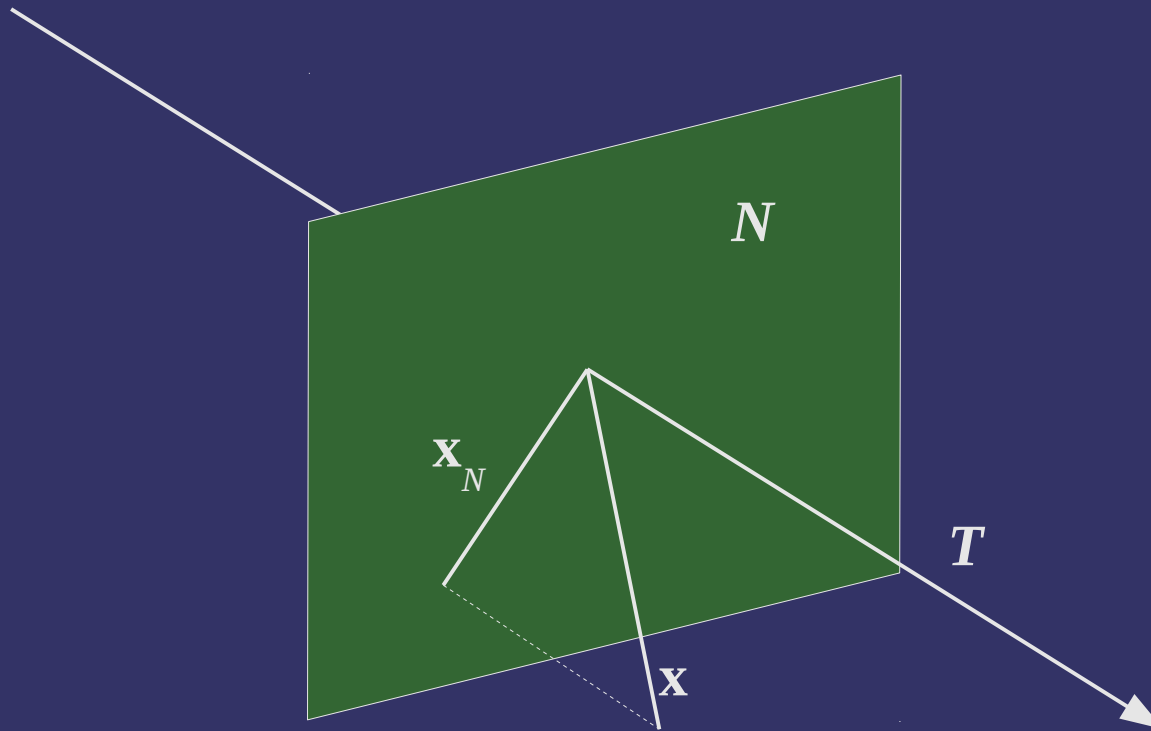


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Terminology – Vector Projections

- ⇒ \mathbf{x}_N is the projection of vector \mathbf{x} onto N
- ⇒ \mathbf{x}_T is the projection of vector \mathbf{x} onto T

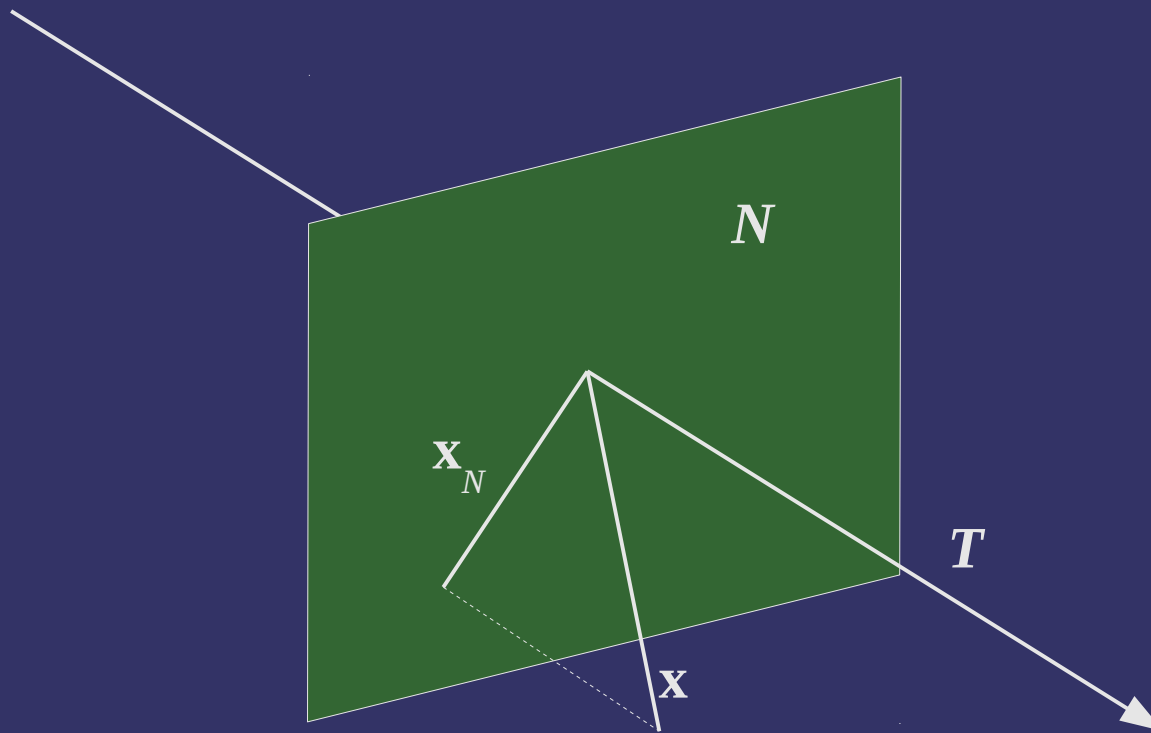


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Terminology – Vector Projections

⇒ How do we project a vector onto a plane?



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Terminology – Vector Projections

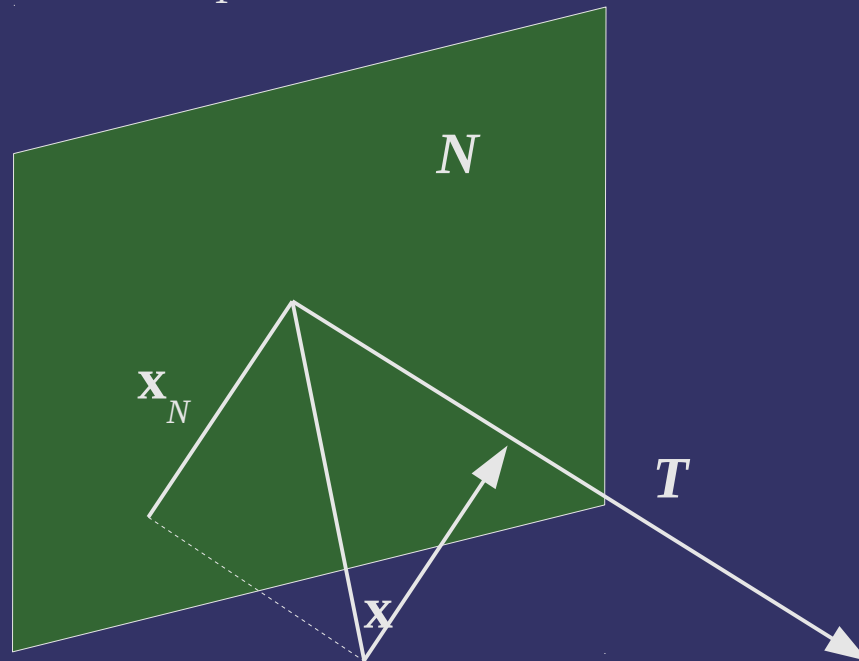
⇒ How do we project a vector onto a plane?

– Fun facts:

– $\mathbf{x}_N = \mathbf{x} - \mathbf{x}_T$

– $|\mathbf{x}_T| = \cos(\mathbf{x}, T) = \mathbf{x} \cdot T \rightarrow \mathbf{x}_T = (\mathbf{x} \cdot T)T$

– $|\mathbf{x}_N| = \sin(\mathbf{x}, T)$



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Diffuse Reflection

- Using this terminology, diffuse reflection can be calculated as:

$$\mathbf{i}_{\text{diffuse}} = k_d \frac{\cos(\mathbf{l}, \mathbf{l}_N)}{|\mathbf{l}| |\mathbf{l}_N|}$$

- Since N and T are orthogonal, we can rewrite this as:

$$\mathbf{i}_{\text{diffuse}} = k_d \frac{\sin(\mathbf{l}, \mathbf{l}_T)}{|\mathbf{l}| |\mathbf{l}_T|}$$



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Specular Reflection

⇒ Phong specular reflection:

$$\mathbf{r} = \mathbf{n} - 2(\mathbf{n} \cdot \mathbf{l})\mathbf{l}$$

$$\mathbf{i}_{\text{specular}} = k_s \mathbf{i}_{\text{light}} \cos(\mathbf{v}, \mathbf{r})^s$$

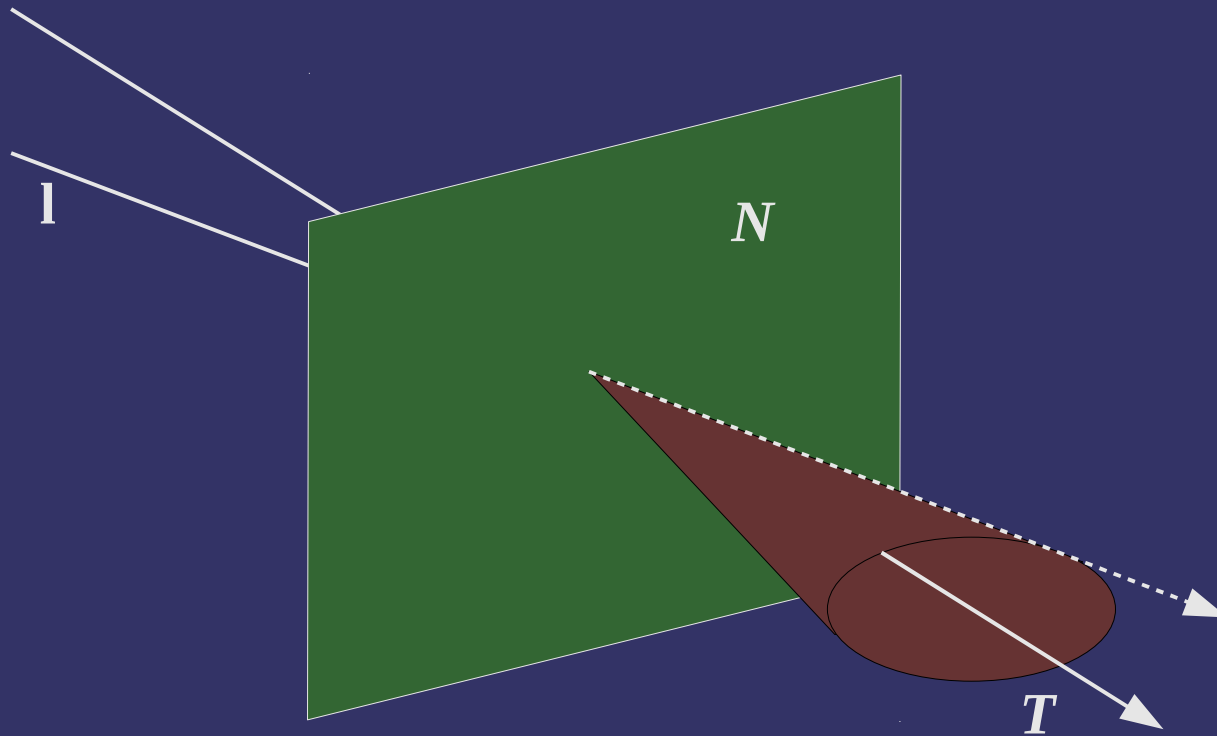


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Specular Reflection

- When $c > 1$, there are infinite possible \mathbf{n} vectors, so there are infinite possible \mathbf{r} vectors



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Fermat's Principle

- Fermat's principle says that light travels on the shortest length path
 - This means that \mathbf{l} , \mathbf{l}_N , and \mathbf{r} are coplanar
 - Skipping a bit of derivation, this means that \mathbf{l}_N is equal to \mathbf{r}_N
 - Skipping a bit more derivation, this means that $\mathbf{v} \cdot \mathbf{r}$ can be calculated as:

$$\mathbf{v} \cdot \mathbf{r} = \mathbf{v}_T \cdot \mathbf{l}_T - |\mathbf{v}_N| |\mathbf{l}_N|$$



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Specular Reflection

⇒ $\mathbf{v} \cdot \mathbf{r}$ can be calculated as:

$$\mathbf{v} \cdot \mathbf{r} = \mathbf{v}_T \cdot \mathbf{l}_T - |\mathbf{v}_N| |\mathbf{l}_N|$$

– But we don't initially know \mathbf{v}_T , \mathbf{l}_T , \mathbf{v}_N , or \mathbf{l}_N



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$$\mathbf{v} \cdot \mathbf{r} = \mathbf{v}_T \cdot \mathbf{l}_T - |\mathbf{v}_N| |\mathbf{l}_N|$$

$$= \mathbf{v}_T \cdot \mathbf{l}_T - \sin(\mathbf{v}, \mathbf{t}) \sin(\mathbf{l}, \mathbf{t})$$



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$$= \mathbf{v}_T \cdot \mathbf{l}_T - \sin(\mathbf{v}, \mathbf{t}) \sin(\mathbf{l}, \mathbf{t})$$

$$= ((\mathbf{v} \cdot \mathbf{t}) \mathbf{t}) \cdot ((\mathbf{l} \cdot \mathbf{t}) \mathbf{t}) - \sin(\mathbf{v}, \mathbf{t}) \sin(\mathbf{l}, \mathbf{t})$$



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$$\begin{aligned} \mathbf{v} \cdot \mathbf{r} &= \mathbf{v}_T \cdot \mathbf{l}_T - |\mathbf{v}_N| |\mathbf{l}_N| \\ &= \mathbf{v}_T \cdot \mathbf{l}_T - \sin(\mathbf{v}, \mathbf{t}) \sin(\mathbf{l}, \mathbf{t}) \\ &= ((\mathbf{v} \cdot \mathbf{t}) \mathbf{t}) \cdot ((\mathbf{l} \cdot \mathbf{t}) \mathbf{t}) - \sin(\mathbf{v}, \mathbf{t}) \sin(\mathbf{l}, \mathbf{t}) \\ &= ((\mathbf{v} \cdot \mathbf{t})(\mathbf{l} \cdot \mathbf{t})(\mathbf{t} \cdot \mathbf{t})) - \sin(\mathbf{v}, \mathbf{t}) \sin(\mathbf{l}, \mathbf{t}) \end{aligned}$$



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Specular Reflection

⇒ $\mathbf{v} \cdot \mathbf{r}$ can be calculated as:

$$\mathbf{v} \cdot \mathbf{r} = \mathbf{v}_T \cdot \mathbf{l}_T - |\mathbf{v}_N| |\mathbf{l}_N|$$

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Specular Reflection

⇒ $\mathbf{v} \cdot \mathbf{r}$ can be calculated as:

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Inherited Self-Shadowing

- ⇒ When $c = 1$, the object has at most 2 sides
 - One side of the surface “self-shadows” the other
 - We get that calculation for free from $\mathbf{n} \cdot \mathbf{l}$



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Inherited Self-Shadowing

- ⇒ When $c = 1$, the object has at most 2 sides
 - One side of the surface “self-shadows” the other
 - We get that calculation for free from $\mathbf{n} \cdot \mathbf{l}$
- ⇒ Consider a surface with a 2D tangent space, T , and a 1D vector field, V
 - If T is used to calculate the illumination, $\mathbf{n}_{\text{surface}} \cdot \mathbf{l}$ works
 - If V is used to calculate the illumination, there is no unique \mathbf{n} to use

Think of bristles on a surface



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Inherited Self-Shadowing

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 - If T is used to calculate the illumination, $\mathbf{n}_{\text{surface}} \cdot \mathbf{l}$ works
 - If V is used to calculate the illumination, there is no unique \mathbf{n} to use
 - If V is used to calculate the illumination, it can *inherit* $\mathbf{n}_{\text{surface}} \cdot \mathbf{l}$ from T
- $$\mathbf{i}_{\text{conditioned}} = \max(\mathbf{n} \cdot \mathbf{l}, 0) (\mathbf{i}_{\text{diffuse}} + \mathbf{i}_{\text{specular}})$$



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Vector Field Shadowing

- ⇒ This shadows the vector field from the surface
 - If the vectors lie outside the surface (e.g., fur) the vector field can obviously shadow itself and the surface
- ⇒ Input light energy is attenuated by:

$$d = h / \sin(\mathbf{t}, \mathbf{l})$$

$$\mathbf{i}_{\text{atten}} = \mathbf{i}_{\text{source}} (1 - \rho)^d$$

- h is the distance from the surface
- ρ is a property of the fur
 - The paper uses $\rho = 0.02$



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Strand Based Anisotropic Lighting

- ⇒ Why limit the use of this lighting model to individual strands?
 - We can treat many types of anisotropic surfaces as a collection of many strands... and apply the same lighting technique!

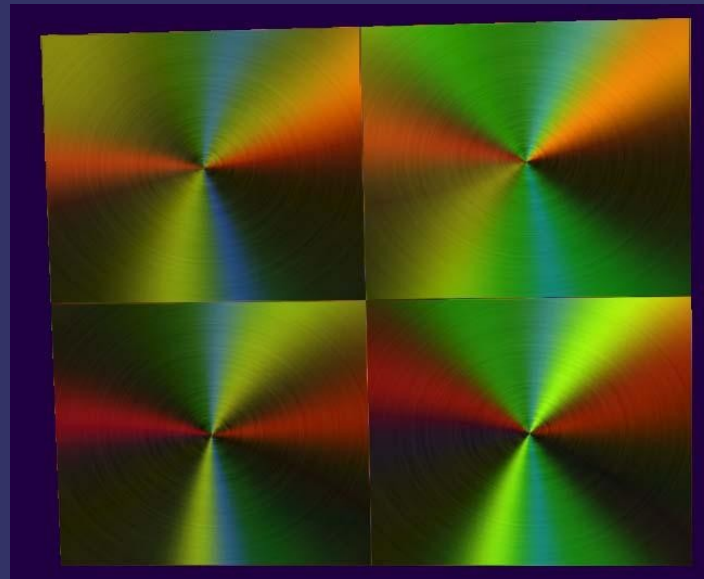


Image from ShaderX, Wordware Publishing, Inc.

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Banks, D. C. 1994. Illumination in diverse codimensions. In *Proceedings of the 21st Annual Conference on Computer Graphics and interactive Techniques SIGGRAPH '94*. ACM, New York, NY, 327-334.

<http://lmi.bwh.harvard.edu/~banks/>

Isidoro, John and Brennan, Chris. "Per-Pixel Strand Based Anisotropic Lighting" in Engel, Wolfgang F. (editor) *ShaderX*, Wordware Publishing, Inc., May 2002.

<http://developer.amd.com/documentation/reading/pages/ShaderX.aspx>



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fakefur

- ⇒ Developed by Dan Goldman at ILM
 - A *much* faster version of the “realfur” algorithm used at ILM for close-up shots



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fakefur

- Makes several simplifying assumptions:
 - Geometry of individual hairs is not visible
 - Hairs are truncated cones
 - The length of each cone is much greater than the radius of either end
 - Can't be used to render 5 o'clock shadow!
 - Radius of the base is greater than the radius of the other end
 - All hairs in an area have identical geometry



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Algorithm Overview

- Compute average hair geometry in sample area
- For each light:
 - Compute hair-over-hair shadow attenuation
 - Compute reflected luminance of hair
 - Compute hair-over-skin shadow attenuation
 - Compute reflected luminance of skin
 - Compute hair / skin visibility ratio
 - Blend skin and hair reflected luminances using hair / skin visibility ratio
- Sum per-light calculated values



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Illumination Function

$$\Psi_{\text{diffuse}} = \mathbf{k}_d \sin(\mathbf{t}, \mathbf{l})$$

$$\Psi_{\text{specular}} = \mathbf{k}_s \left((\mathbf{t} \cdot \mathbf{l})(\mathbf{t} \cdot \mathbf{v}) + \sin(\mathbf{t}, \mathbf{l}) \sin(\mathbf{t}, \mathbf{v}) \right)^p$$

$$\Psi_{\text{hair}} = \Psi_{\text{diffuse}} + \Psi_{\text{specular}}$$

⇒ Why is sine used instead of cosine?



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Illumination Function

$$\Psi_{\text{diffuse}} = k_d \sin(\mathbf{t}, \mathbf{l})$$

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$$\Psi_{\text{hair}} = \Psi_{\text{diffuse}} + \Psi_{\text{specular}}$$

⇒ Why is sine used instead of cosine?

- We treat the hair as having dimension = 1
 - There are infinite possible normals
 - There is only one tangent

This should look familiar!



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Illumination Function

$$\Psi_{\text{diffuse}} = \mathbf{k}_d \sin(\mathbf{t}, \mathbf{l})$$

$$\Psi_{\text{specular}} = \mathbf{k}_s \left((\mathbf{t} \cdot \mathbf{l})(\mathbf{t} \cdot \mathbf{v}) + \sin(\mathbf{t}, \mathbf{l}) \sin(\mathbf{t}, \mathbf{v}) \right)^p$$

$$\Psi_{\text{hair}} = \Psi_{\text{diffuse}} + \Psi_{\text{specular}}$$

⇒ What's wrong here?



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Illumination Function

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$$\Psi_{\text{hair}} = \Psi_{\text{diffuse}} + \Psi_{\text{specular}}$$

⇒ What's wrong here?

- Lacks directionality
 - Hairs are fully lit even if \mathbf{l} is opposite \mathbf{v}
- Fix this by adding some new attenuation factors



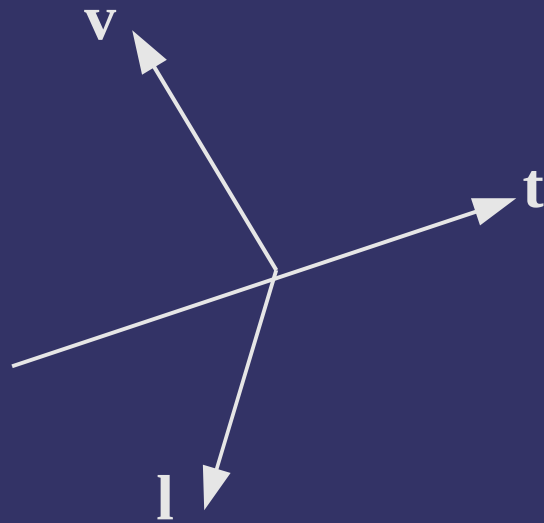
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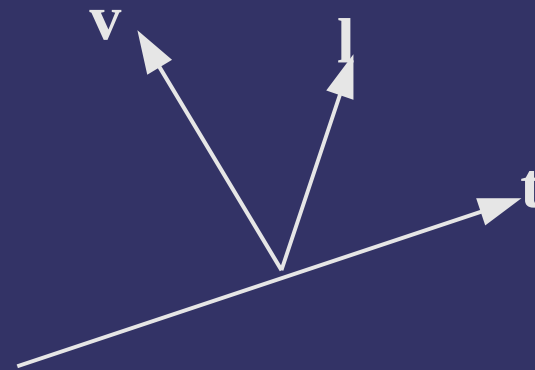
Relative Directionality

$$\kappa = \frac{(\mathbf{t} \times \mathbf{l}) \cdot (\mathbf{t} \times \mathbf{v})}{|\mathbf{t} \times \mathbf{l}| |\mathbf{t} \times \mathbf{v}|}$$

- $\kappa > 0$ when \mathbf{l} and \mathbf{v} are on the same side of the hair (frontlighting)
- $\kappa < 0$ when \mathbf{l} and \mathbf{v} are on opposite sides of the hair (backlighting)



Back lighting



Front lighting



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Directional Attenuation Factor

$$f_{dir} = \frac{1+\kappa}{2} \rho_{reflect} + \frac{1-\kappa}{2} \rho_{transmit}$$

- $\rho_{reflect}$ and $\rho_{transmit}$ are parameters of the hair on the range $[0, 1]$
- White and gray hairs have $\rho_{reflect}$ and $\rho_{transmit}$ equal or nearly equal
- Colored hairs have $\rho_{reflect} > \rho_{transmit}$



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Directional Attenuation Factor

$$f_{dir} = \frac{1+\kappa}{2} \rho_{reflect} + \frac{1-\kappa}{2} \rho_{transmit}$$

- $\rho_{reflect}$ and $\rho_{transmit}$ are parameters of the hair on the range [0, 1]
- White and gray hairs have $\rho_{reflect}$ and $\rho_{transmit}$ equal or nearly equal
- Colored hairs have $\rho_{reflect} > \rho_{transmit}$
- Unless you're a kitten...



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Self-Shadowing

- Controlled by a second attenuation factor and 3 new parameters:

$$f_{\text{surface}} = 1 + \rho_{\text{surface}} \left(\text{smoothstep}(\mathbf{n} \cdot \mathbf{l}, \theta_{\text{min}}, \theta_{\text{max}}) - 1 \right)$$

- ρ_{surface} controls the amount of self-shadowing
- θ_{min} is the minimum angle where shadowing occurs
- θ_{max} is the angle beyond which there is total occlusion



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Fur Opacity

- How much of the surface *below* the fur can be seen through the fur?
 - Contributing factors:
 - Hair density: More hairs result in more occlusion
 - Hair size: Larger (thicker) hairs individually occlude more
 - Hair orientation: Hairs “laying down” occlude more than hairs on end
 - Orientation relative to both the viewer and the underlying surface are factors

On end
Laying down



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Fur Opacity

- ⇒ How much of the surface *below* the fur can be seen through the fur?

$$\alpha_f = 1 - \frac{1}{e^{d a_h g(\mathbf{v}, \mathbf{t}, \mathbf{n})}}$$
$$g(\mathbf{v}, \mathbf{t}, \mathbf{n}) = \frac{\sin(\mathbf{v}, \mathbf{t})}{\mathbf{v} \cdot \mathbf{n}}$$
$$a_h = l_{\text{hair}} (r_{\text{base}} + r_{\text{top}}) / 2$$

- d is the local hair density
- a_h is the projection of the surface area of a hair onto the view plane



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Putting It All Together

- Put the attenuation factors together with the opacity and skin color:

$$\Psi_{\text{hair}} = f_{\text{dir}} f_{\text{surface}} (\Psi_{\text{diffuse}} + \Psi_{\text{specular}})$$

$$\lambda_{\text{skin}} = \mathbf{k}_{\text{light}} (1 - \alpha_f) \Psi_{\text{skin}}$$

$$\lambda_{\text{hair}} = \mathbf{k}_{\text{light}} \left(1 - \frac{\alpha_f}{2}\right) \Psi_{\text{hair}}$$

$$f = \alpha_f \lambda_{\text{hair}} + (1 - \alpha_f) \lambda_{\text{skin}}$$

- Ψ_{skin} is calculated by some other means



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Implementing BRDFs in Real-Time

- BRDF formulations assume integration over all incoming light in the positive hemisphere
 - Clearly impractical for real-time rendering!
 - Not very practical for off-line rendering either...
- Four high-level strategies:
 - Only implement point lights
 - Direction implementation
 - Factorization
 - Reflection map based pre-filtering / pre-calculation
 - Monte Carlo sampling



– Deferred shading based techniques

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Point Light Direct Implementation

- ⇒ Use \mathbf{l} for ω_i and \mathbf{v} for ω_o and directly implement the math
 - We already do this for Phong lighting
 - More complex lighting equations can be prohibitively expensive
 - Since we're *not* integrating over the hemisphere, multiply the BRDF by π



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Factorization

- ⇒ Expensive equations can be factored into sums or products of functions of fewer variables
 - Each input vector (i.e., \mathbf{v} , \mathbf{l} , \mathbf{h} , \mathbf{n} , etc.) or dot-product of vectors becomes an input to one function
 - Each function is stored in some sort of texture
 - This technique works really well for sampled BRDFs
- ⇒ Using two textures, the Poulin-Fournie anisotropic satin BRDF can be implemented as:

$$\alpha p(\mathbf{v})q(\mathbf{h})p(\mathbf{l})$$

- $p()$ and $q()$ represent texture look-ups and α is a special scaling factor



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Factorization

⇒ Remember the Banks BRDF for strands:

$$\mathbf{v} \cdot \mathbf{r} = (\mathbf{v} \cdot \mathbf{t})(\mathbf{l} \cdot \mathbf{t}) - \left(\sqrt{1 - (\mathbf{v} \cdot \mathbf{t})^2} \sqrt{1 - (\mathbf{l} \cdot \mathbf{t})^2} \right)$$



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Factorization

➤ Remember the Banks BRDF for strands:

$$\mathbf{v} \cdot \mathbf{r} = (\mathbf{v} \cdot \mathbf{t})(\mathbf{l} \cdot \mathbf{t}) - \left(\sqrt{1 - (\mathbf{v} \cdot \mathbf{t})^2} \sqrt{1 - (\mathbf{l} \cdot \mathbf{t})^2} \right)$$

- Note that $\mathbf{v} \cdot \mathbf{r}$ is a function of two dot-products
- Store all possible values of $\mathbf{v} \cdot \mathbf{r}$ in a 2D texture and sample this texture using $\mathbf{v} \cdot \mathbf{t}$ and $\mathbf{l} \cdot \mathbf{t}$



Image from ShaderX, Wordware Publishing, Inc.

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<http://www.cgl.uwaterloo.ca/Projects/rendering/Shading/database.html>

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Reflection Maps

- Reflection maps present additional challenges
 - Decent lighting require multiple samples
- As with the Phong lighting model, reflection maps can be pre-filtered using complex BRDFs
 - Doesn't work well with dynamic env. maps
 - Doesn't work *at all* with anisotropic BRDFs
 - The ideal reflection vector isn't enough information!



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Grid Sampling

- ⇒ Sample the reflection map at multiple, predetermined locations, use the sample vectors and the sampled values in the lighting equation



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Grid Sampling

- Sample the reflection map at multiple, predetermined locations, use the sample vectors and the sampled values in the lighting equation
 - Might not sample the most important vectors for the lighting equation
 - For most equations, samples closer \mathbf{r} are more important



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Grid Sampling

- Sample the reflection map at multiple, predetermined locations, use the sample vectors and the sampled values in the lighting equation
 - Might not sample the most important vectors for the lighting equation
 - For most equations, samples closer \mathbf{r} are more important
 - Might not sample the most important vectors for the reflection map
 - If most of the reflection map is dark with just a few bright spots, those bright spots are more important
 - This problem is especially difficult to solve



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Monte Carlo Integration

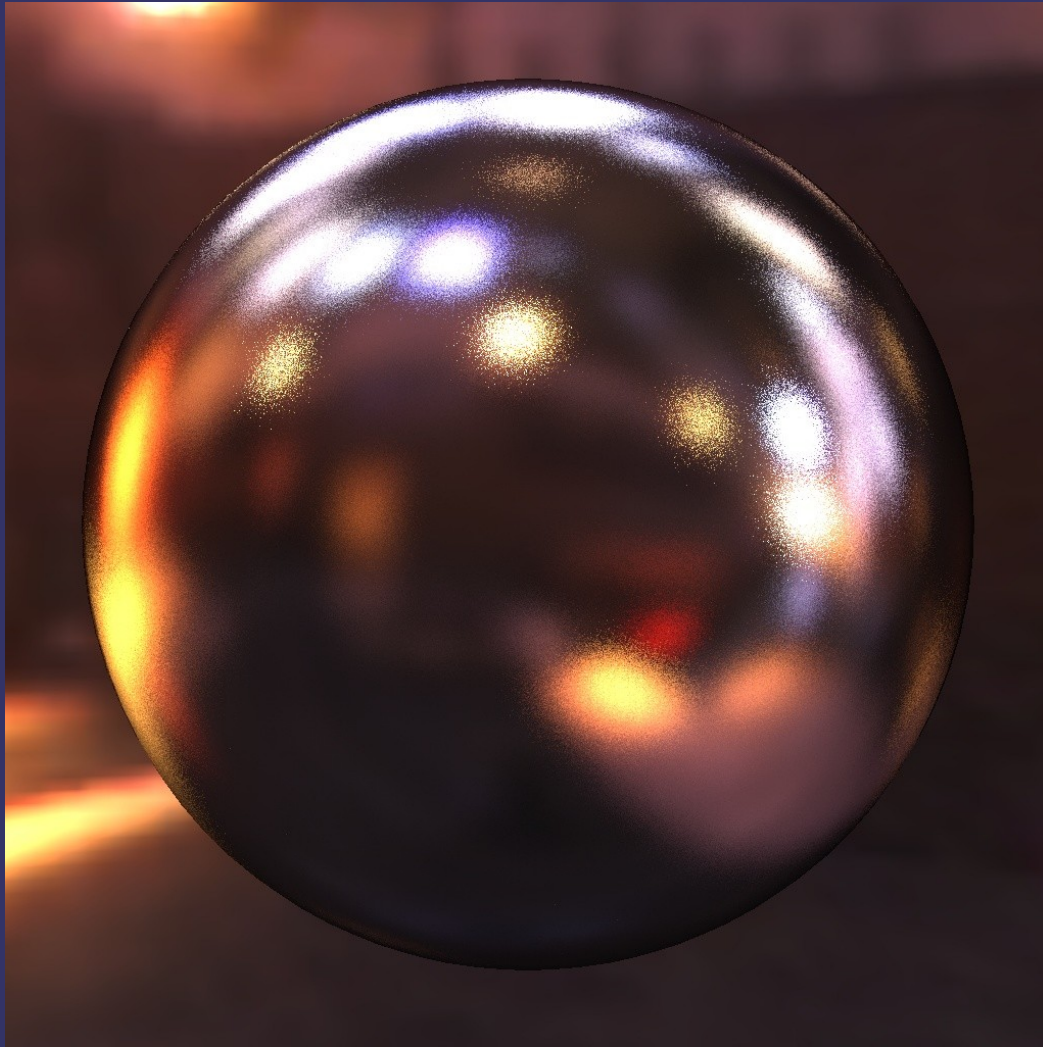
- Instead of sampling at regular intervals, sample at pseudo-random locations



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Monte Carlo Integration



Images rendered with 40 samples per-fragment



Images from "Real-time Shading with Filtered Importance Sampling"
http://graphics.cs.ucf.edu/gpusampling/filter_is_intel.ppt
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Monte Carlo Integration

- Instead of sampling at regular intervals, sample at pseudo-random locations
 - Must sample many locations to eliminate noise
 - Where “many” may mean *thousands*
 - Or determine the random locations with a BRDF-dependent probability density function (PDF)
 - Several of the papers from this term include a PDF for the BRDF
 - Still several problems:
 - Generating good random numbers on the GPU is hard
 - Requires quite a few samples
 - Colbert and Křivánek found that around 40 looks good



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Monte Carlo Integration

⇒ Monte Carlo estimator for a BRDF:

$$L(\mathbf{v}) \approx \frac{1}{n} \sum_{k=1}^n \frac{L_i(\mathbf{u}_k) f(\mathbf{u}_k, \mathbf{v}) \cos \theta_{\mathbf{u}_k}}{p(\mathbf{u}_k, \mathbf{v})}$$

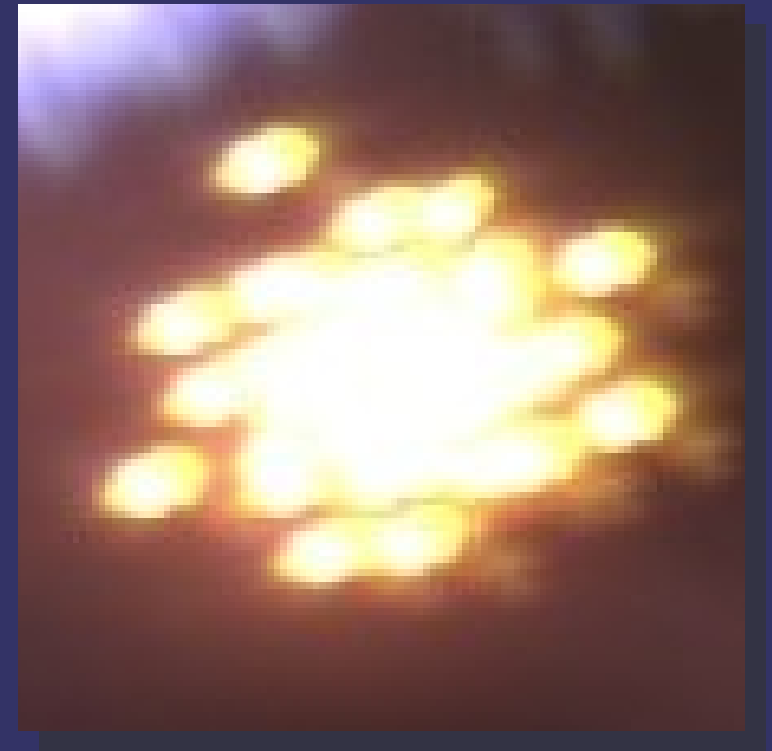
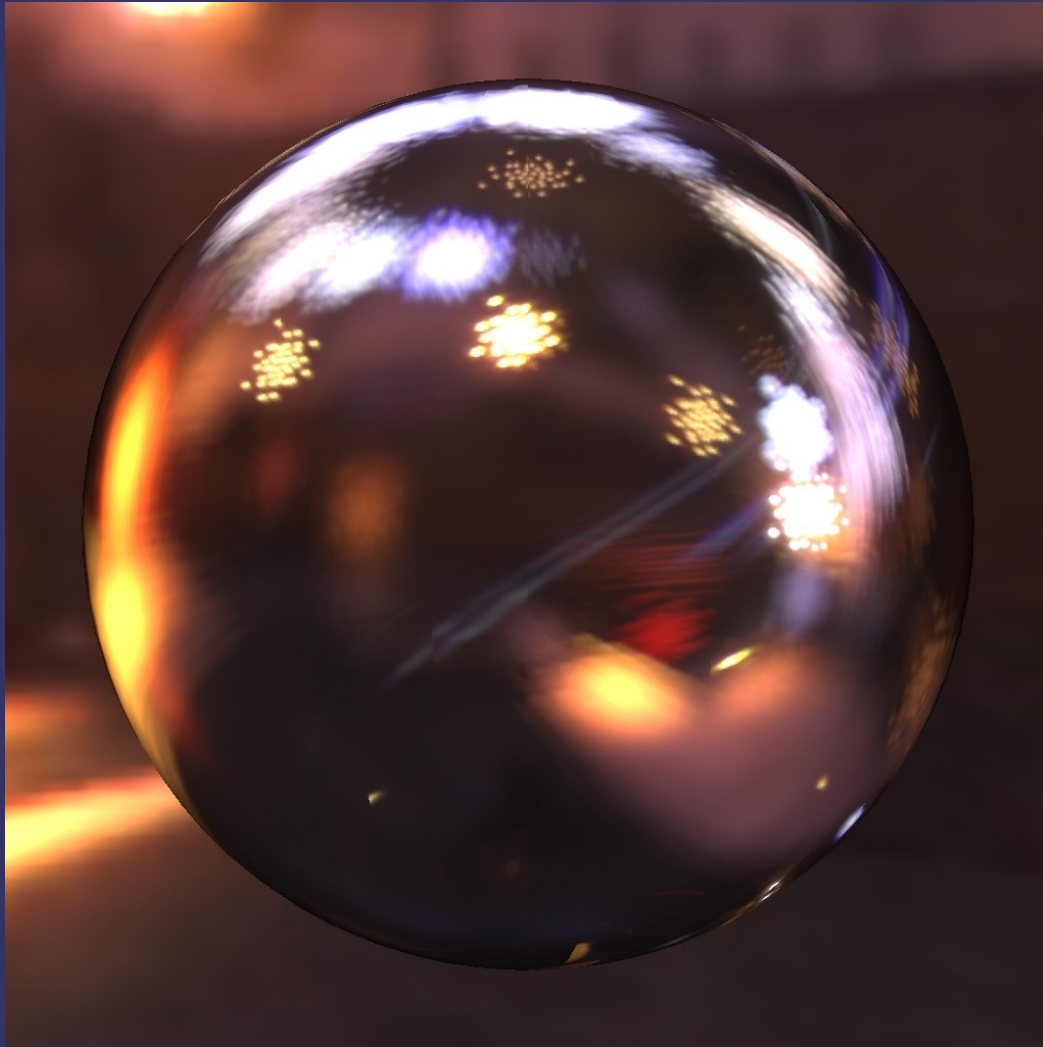
- p is the PDF
- \mathbf{u}_k is a random light direction generated based on the PDF
 - Typically generate a uniform random value and remap it based on the PDF



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Monte Carlo Integration



Images rendered with 40 samples per-fragment



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Monte Carlo Integration

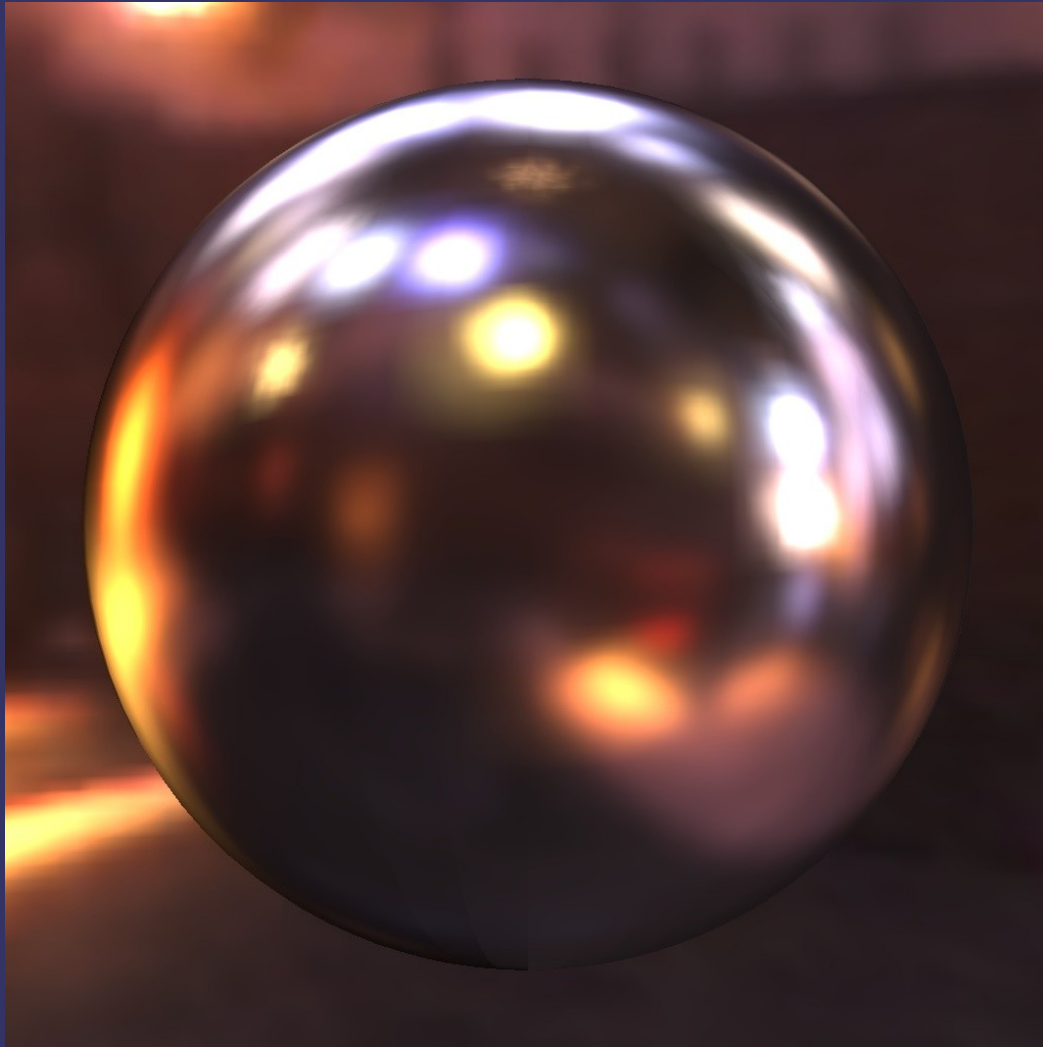
- Deterministic importance sampling causes unacceptable aliasing effects
 - Less important samples (i.e., less probable) are low-weighted individual points
 - Observe that neighbors of less probably samples are unlikely to be sampled
 - Allow those neighbors to contribute by using the PDF to select a mipmap level in the reflection map
 - Higher mipmap levels average larger regions into a single texel
 - Cube maps have weird distortion away from the axes, so a different type of reflection map should be used



The paper suggests dual-paraboloid maps
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Monte Carlo Integration



Images rendered with 40 samples per-fragment



Images from "Real-time Shading with Filtered Importance Sampling"
http://graphics.cs.ucf.edu/gpusampling/filter_is_intel.ppt
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Colbert, M. and Křivánek, J. 2007. “Real-time shading with filtered importance sampling.” In *ACM SIGGRAPH 2007 Sketches* (San Diego, California, August 05 - 09, 2007). SIGGRAPH '07. ACM, New York, NY, 71. <http://graphics.cs.ucf.edu/gpusampling/>
http://en.wikipedia.org/wiki/Monte_Carlo_integration



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Volumetric Fur

- Close-up, fur appears as a volumetric effect
- Kajika and Kay presented an algorithm at SIGGRAPH '89 implementing fur via 3D textures
 - Volumetric textures are *very* memory intensive
 - Kajika and Kay's model involves several computationally expensive steps
- Not practical for real-time
 - There has to be a different way!

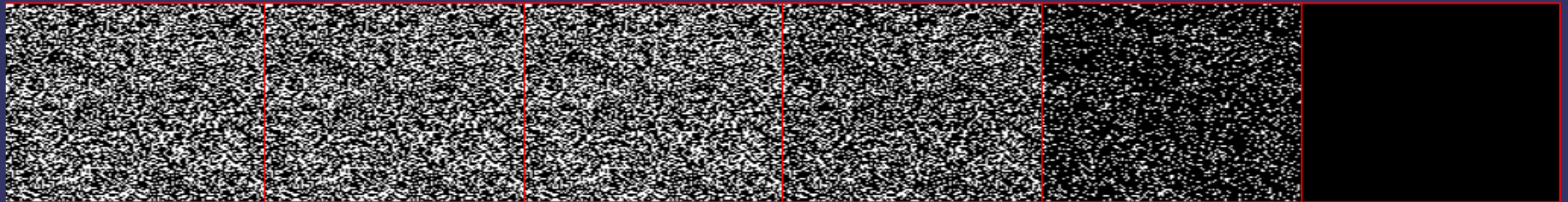


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Shells and Fins

- Instead of a 3D texture, fur can be implemented with a “stack” of 2D textures
 - Each layer in the stack represents the fur at a different depth



- Draw each layer in a progressively larger “shell” around the original object geometry



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Shells and Fins

⇒ Drawing loop:

- Draw base object with inner-most (call it level 0) fur texture
 - Disable alpha blending
 - Enable z-testing
 - Enable z-writing
- Draw base geometry moved out some small step along the normals
 - Enable alpha blending
 - Enable z-testing
 - Disable z-writing

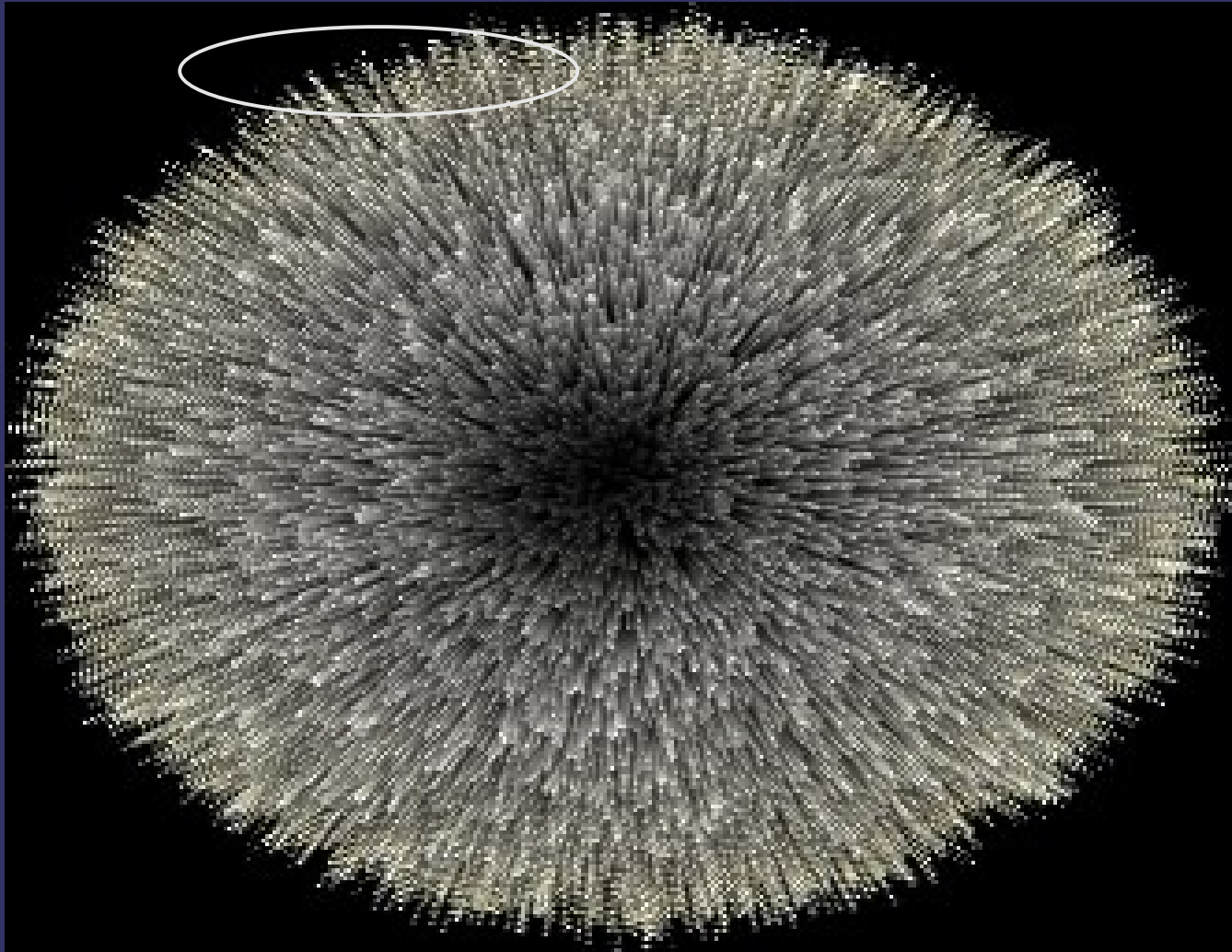


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Shells and Fins

➤ *But this looks bad along the silhouette*



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Shells and Fins

- Add fin geometry to each polygon
 - Create fin textures to look like side-on view of fur
 - Draw fin after drawing all shells
 - Enable alpha blending
 - Enable z-testing
 - Disable z-writing



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Shells and Fins

- Generate fin geometry in the vertex shader:
 - Draw each vertex *twice*
 - Once with $w = 0$
 - Once with $w = 1$
 - Use the w value to determine whether or not to extrude the vertex in the normal direction
 - Draw the vertices as two triangles:
 - One with vertices 0, 1, 1
 - The other with vertices 1, 0, 0

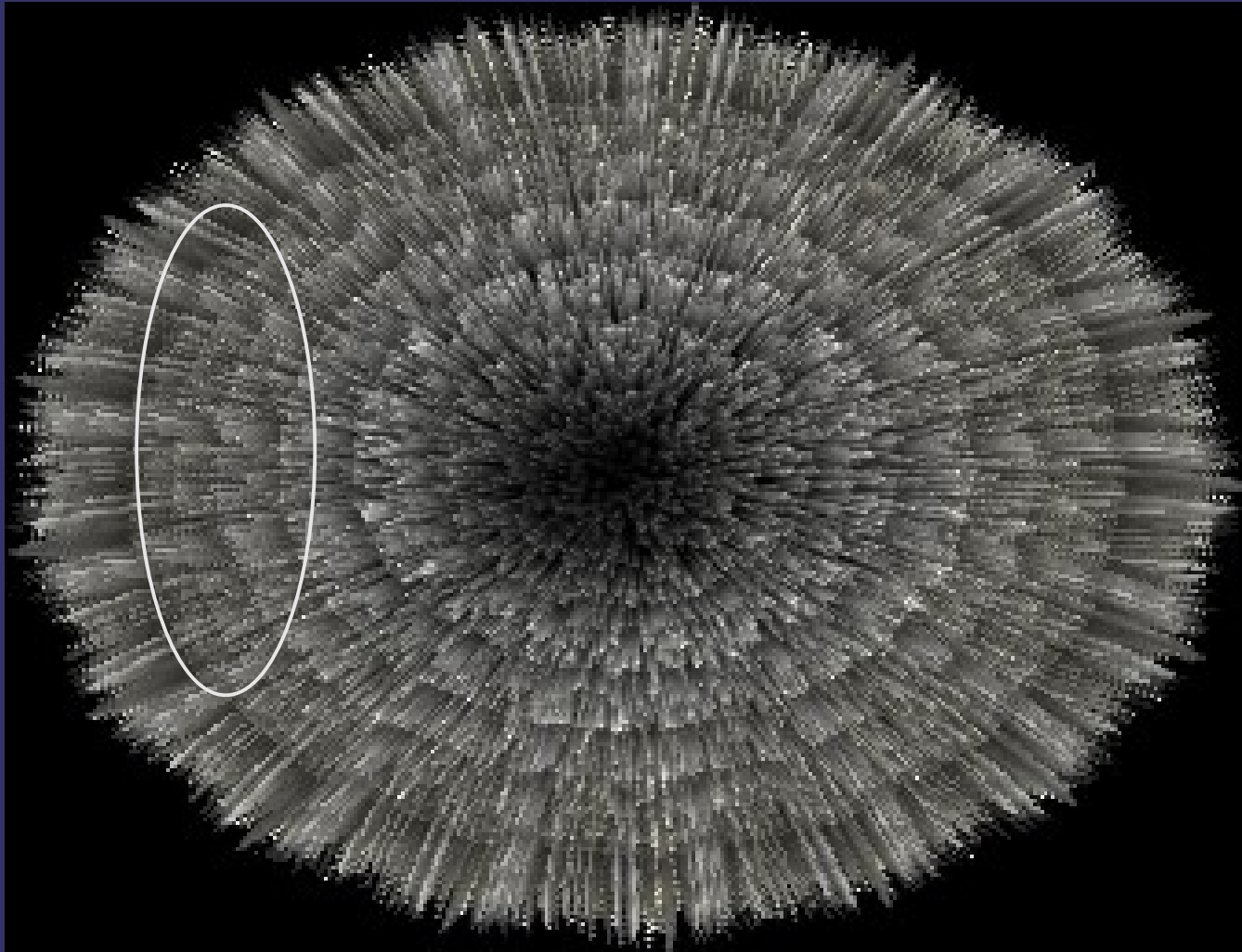


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Shells and Fins

➤ *But this looks bad in non-silhouette areas*



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Shells and Fins

- Gradually blend in fins as they approach the silhouette

$$\alpha_{\text{fin}} = \max(0, 2|\cos(\mathbf{v}, \mathbf{n}_{\text{fin}})| - 1)$$

- We don't really have a fin normal...what to do?



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Shells and Fins

- Gradually blend in fins as they approach the silhouette

$$\alpha_{\text{fin}} = \max(0, 2|\cos(\mathbf{v}, \mathbf{n}_{\text{fin}})| - 1)$$

- We don't really have a fin normal...what to do?
 - The surface's normal is the fin's tangent

$$\alpha_{\text{fin}} = \max(0, 2|\sin(\mathbf{v}, \mathbf{n}_{\text{surface}})| - 1)$$

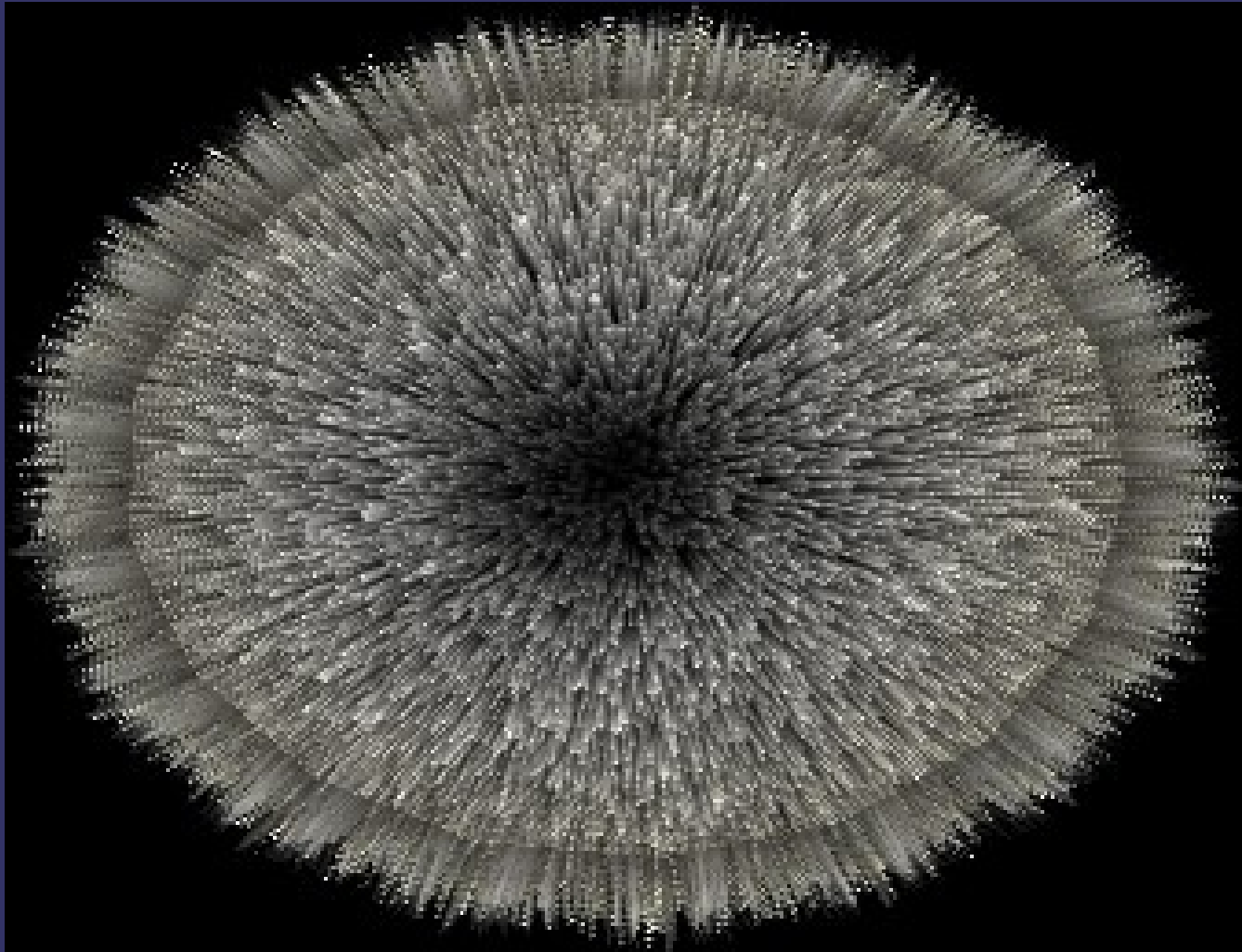


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Shells and Fins

⇒ Alpha blended fins



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Lighting Shells and Fins

- ⇒ Use the surface normal as the direction of the hair

$$\mathbf{k} = \mathbf{k}_d \sin(\mathbf{n}_{\text{surface}}, \mathbf{l})^{p_d} + \mathbf{k}_s \sin(\mathbf{n}_{\text{surface}}, \mathbf{h})^{p_s}$$

- p_d and p_s are diffuse and specular exponents
- Similar to Goldman's fakefur lighting model

- ⇒ A little trig-identity love gets us:

$$\begin{aligned} \mathbf{k} &= \mathbf{k}_d (1 - \cos(\mathbf{n}_{\text{surface}}, \mathbf{l})^{p_d/2}) + \mathbf{k}_s (1 - \cos(\mathbf{n}_{\text{surface}}, \mathbf{h})^{p_s/2}) \\ &= \mathbf{k}_d (1 - (\mathbf{n}_{\text{surface}} \cdot \mathbf{l})^{p_d/2}) + \mathbf{k}_s (1 - (\mathbf{n}_{\text{surface}} \cdot \mathbf{h})^{p_s/2}) \end{aligned}$$



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Lighting Shells and Fins

⇒ No shadowing happens!

- Fur near the skin is occluded by the fur above it
- Add a shadowing term to falloff to a minimum value linearly with the distance from the outermost shell

$$s = \frac{d(1 - s_{min})}{d_{max}} + s_{min}$$

- d is the current shell distance
 - $d = 0$ is the shell closest to the skin
- d_{max} is the total number of shells
- s_{min} is the minimum amount of light reaching the bottom layer



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Thorough overview of the various real-time fur methods.

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Next week...

- Quiz #3
- Non-photorealistic rendering
 - Cel (toon) shading
 - Silhouette edge rendering
 - Technical illustration
- Begin post-processing / image space effects



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